Course Structure- Overview

Basic of Device Electronics	Basics of Digital Electronics	Basics of C
 Resistors, Capacitors, Inductors. PN-Junction. Diodes. Transistor. MOSFET/CMOS. Interpretation Data Sheet. Half-Wave Rectifiers/ Full-Wave Rectifier. Power Supply 3.3V,5.0V,12.0V, Voltage regulators. Crystals Switches, Relays. 7-Segment 555 Timers in AS/MS/BS 	 Number System – Binary, Hex, Decimal, BCD System. Addition/Subtraction of binary, 2's complements. Interconversion of number system. Logic Gates – AND/OR/NOR/EXOR. Filip-flop, Memory element. Mux- De-Mux, Decoders. Shift Registers. Counters. 	 Getting Started Scope of Variables Control flow Constructs The C Pre-processor More ON Functions Bit Manipulation Strings & Arrays Pointers Structures Unions

Basic of Embedded Systems	Advanced C	Advanced Embedded Systems
 Microprocessor Basic Concepts and Review Microcontroller Basic Concepts and Review Embedded C & Integrated Development Environment Introducing ARM Architecture 	 Structure and union Function Pointers Dynamic memory allocation File operations String operations 	 Introduction Overview of Architecture of 8051 Low-level Programming Concepts Middle Level Programming Concepts On-Chip Peripherals External Interfaces Protocols Keil's RTX51 Tiny / Pumpkin's Salvo Selective Discussion during Project Development

Tools Including S/W and H/W for Embedded Systems Training			
Mu	ltimeter	Log	ic Analyzer
•	Measuring Voltage/Current/Registers	•	What is Logic Analyzer
•	Measuring continuity	•	How to use Logic Analyzer
•	Introducing BBT – Baring Board Test	•	What is the use of a logic analyser?
		•	For which protocol we can use a logic analyser

Course Structure- Detailed

Basics of C		
 CHAPTER 1: GETTING STARTED What is C? Data Types Variables Naming Conventions for C Variables Printing and Initializing Variables 	CHAPTER 2: SCOPE OF VARIABLES Block Scope Function Scope File Scope Program Scope The auto Specifier The static Specifier The register Specifier The autorn Specifier 	
	 The extern Specifier The extern Specifier The extern Specifier 	
 CHAPTER 3: CONTROL FLOW CONSTRUCTS If if else while for Endless Loops do while break and continue switch 	CHAPTER 4: THE C PREPROCESSOR #define Macros #include Conditional Compilation #ifdef #ifndef	
 else Ir CHAPTER 5: MORE ON FUNCTIONS Function Declarations Function Prototypes Returning a Value or Not Arguments and Parameters Organization of C Source Files Extended Example 	 CHAPTER 6: BIT MANIPULATION Defining the Problem Space A Programming Example Bit Wise Operators Bit Manipulation Functions Circular Shifts 	
 CHAPTER 7: STRINGS & ARRAY Fundamental Concepts Aggregate Operations String Functions Array Dimensions An Array as an Argument to a Function String Arrays Example Programs 	 CHAPTER 8: POINTERS (PART 1) Fundamental Concepts Pointer Operators and Operations Changing an Argument with a Function call Pointer Arithmetic String Functions with Pointers Pointer Difference Prototypes for String Parameters Relationship Between an Array and a Pointer The Pointer Notation *p++ 	
 CHAPTER 9: STRUCTURES Fundamental Concepts Describing a Structure Creating Structures Operations on Structures Functions Returning Structures Passing Structures to Functions Pointers to Structures Array of Structures Functions Returning a Pointer to a Structure Structure Padding 	 CHAPTER 10: UNIONS typedef – New Name for an Existing Type Bit Fields Unions Non-Homogeneous Arrays Enumerations 	

Advanced C			
 CHAPTER 1: STRUCTURES AND UNIONS Combination of Structure and union. Bit fields in Structure. Pointers to structure and union. The advantage of Structure and union CHAPTER 3: DYNAMIC MEMORY ALLOCATION Malloc Calloc free re-alloc 	 CHAPTER 2: FUNCTION POINTERS Microcontroller Basic Concepts and Review Function pointers. Callbacks Advantage/use of functions pointers CHAPTER 4: FILE OPERATIONS Opening A file Closing a file Writing some data in a file and reading back and printing. The different mode in which file can be open and write. 		
CHAPTER 5: STRING OPERATIONS Srtcpy strcmp strcat strlen strstr 			

Basics of Embedded Systems			
 CHAPTER 1: BASICS OF EMBEDED SYSTEMS Definition Nomenclature Buses – Address, Data, and Control Architecture Interfacing memory & I/O devices Programming (Assembly) Monitor program 	 CHAPTER 2: BASICS OF MICROCONTROLLER Architecture Interfacing memory & I/O devices Programming (Assembly) Assignments 		
 CHAPTER 3: EMBEDDED C & INTEGRATED DEVELOPMENT Embedded C Programming Data types Pointers Arrays Pointer functions Loops 	 CHAPTER 4: INTRODUCING ARM ARCHITECTURE Induction of ARM Architecture ARM7TDMI Difference between ARM9/ARM11 Different ARM concepts The advantage of ARM. 		

Advanced Embedded Systems- Microcontroller Intel 8051		
 CHAPTER 1: INTRODUCTION Basic Introduction Microprocessor vs Microcontroller CISC vs RISC 	 CHAPTER 2: OVERVIEW OF 8051 ARCHITECTURE Processor Core and Functional Block Diagram Description of memory organization Overview of ALL SFR's and their basic functionality 	
 CHAPTER 3: LOW LEVEL PROGRAMMING CONCEPTS Addressing Modes Instruction Set and Assembly Language (ALP) Developing, Building and Debugging ALP's 	 CHAPTER 4: MIDDLE LEVEL PROGRAMMING CONCEPTS Cross Compiler Embedded C Implementation, prog. * Debugging Differences from ASNSI-C Memory Models Library reference Use of #pragma directive Functions, Parameter passing and return types 	
 CHAPTER 5: ON-CHIP PERIPHERALS Ports: Input/output Timers & Counters Interrupts, UART 	 CHAPTER 6: EXTERNAL REFERENCES LEDS Switches (Momentary type, Toggle type) Seven Segment Display: (Normal mode, BCD mode, Internal Multiplexing & External Multiplexing) LCD (4bit, 8bit, Busy Flag, Custom Character Generation) Keynad Matrix 	
 CHAPTER 7: PROTOCOLS I2C (EEPROM), SPI (EEPROM) 	CHAPTER 8: KELL'S RTX51 TINY/PUMPKIN'S SALVO Overview Specifications Multi-Tasking Programs Multi-Tasking Programs RTX51 Tiny Programs Theory of Operation Timer Tick Interrupt Task Management & Scheduler Events Round-Robin & Co-operative Task Switching Idle Task Stack Management Function Reference Porting on to H/W Implementation Examples	
 CHAPTER 9: SELECTIVE DISCUSSION DURING PROJECT DEVELOPMENT A/D & D/A Converter Stepper motor, DC Motor I2C Protocol (RTC:800583,DS1307 ADC:PCF8591, DS1621) SPI Protocols (ADC:MCP3001) IR Communications (Phillips RC5 Protocol) ZIGBEE, GSM, GPS, USB, MMC & SD Ethernet MAC, CAN Protocol 		